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Zero-Current-Switch Quasi-Resonant Boost Converter in Power Factor Correction Applications

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Abstract- A modified zero-current-switched quasi-resonant (ZCS-QR) boost converter is employed in a power factor correction (PFC) application. The main goal is to achieve a small-size low-noise PFC circuit based on single-switch boost topology. A clamp diode has been added to avoid the voltage ringing problem that is originally generated across the ZCS-QR switch during its turn-off period. The converter operation states after clamp diode application are presented. The PFC circuit control scheme implementation is also described. An experimental circuit with 100 V rms ac of 50 Hz input and 330 V dc output has been built. A high efficiency of 90% and the proof of compliance to the IEC61000-3-2 class D have been confirmed by experiment.

Key words: PFC, Boost Converter, ZCS-QR, single-switch

I. INTRODUCTION

Power factor correction (PFC) circuit becomes mandatory in off-line power application to comply with IEC61000-3-2. The standard specifies harmonics limit up to 39th and applies to most electrical equipment with input power greater than 75 W [1]. However, as most PFC circuits are implemented by power electronics approach, it should also pass the electromagnetic interference (EMI) standards such as EN50081 or CISPR Publication 22.

Incorporating a topology that generates as small EMI as possible could ease further EMI filtering effort. The zero-voltage-switched (ZVS) topology is characterized by that capability [2]. However, this solution normally employs more than one active switch if being applied into PFC application circuits [3, 4, and 5]. It leads to complex control scheme and high production cost.

Providing other option; this paper presents a single-switch PFC incorporating full-wave zero-current-switched quasi-resonant (ZCS-QR) boost converter. Like its ZVS counterpart, ZCS topology is also known to generate less EMI [2, 6].

Interesting characteristics of the ZCS-QR solution while being applied to PFC applications are: (1) parasitic elements around converter would be less excited if compared to hard switching solution [6], (2) its inherent variable frequency control mechanism is capable to spread the EMI spectrum [7, 8]. Those points give positive effect to the EMI level reduction.

The proposed topology also has other advantage. This ZCS-QR PFC may be operated over higher switching frequency without sacrificing too much of its efficiency. High operating frequency condition leads toward smaller reactive components requirement. It results in less occupied space, weight reduction, and cheaper solution.

Fig. 1. Conventional full-wave ZCS-QR boost topology

Fig. 2. vs and iLr under severe ringing voltage

Fig. 3. Proposed full-wave ZCS-QR boost topology
II. ZCS-QR BOOST PROBLEM AND SOLUTION

A conventional ZCS-QR boost converter is depicted in Fig. 1. In real application, the main switch $S$ of that circuit has certain value of parasitic capacitance $C_s$. During $S$ turn-off period, $C_s$ and the resonant inductor $L_r$ construct a parallel resonance circuit. At that moment, body diode $D_s$ reverse recovery current excites the resonant circuit. This generates voltage ringing as depicted in Fig. 2.

This ringing condition may excite parasitic circuits around $S$. It results in higher EMI level of the PFC circuit.

The voltage ringing also forces designer to use higher voltage rating MOSFET. It is because the voltage level of that ringing may be very high; depend on the quality factor $Q$ of the resonant $C_s-L_r$ circuit.

In this work, a clamp diode $D_c$ is added to the ZCS-QR circuit to alleviate the ringing problem. The modified circuit is shown on Fig. 3. Result of this modification on the key waveform of the ZCS-QR switch is depicted in Fig. 4.

III. THE PROPOSED CONVERTER’S WORKING STATES

Fig. 5 depicts the proposed ZCS-QR boost converter key waveforms. The circuit operating conditions of that waveforms are $V_i=100$ V, $V_o=360$ V, $I_i=2.38$ A, $I_o=0.6$ A, and $f_s=128$ kHz. It can be inferred from that figure that the modified ZCS-QR boost converter could be divided into six operating states as shown on Fig. 6. a to f.

Fig. 6. a to d show similar working stages as in a conventional full-wave ZCS-QR boost converter. However, Fig. 6. e and f are specific to this proposed topology.

It could be seen from Fig. 6. e that $D_c$ forces $V_i$ be instantaneously equal to $V_o$ during its turn-off period. This completely eliminates the voltage ringing possibility.

Fig. 6. f pointed out that during the last cycle, input inductor current ($I_i$) is divided into boost diode current ($I_{D_b}$) and the clamp diode current ($I_{D_c}$). Therefore, it should be realized that this proposed topology is characterized by:

1. Zero-current-transition will be occurred during switch turn-off action as long as limit in (1) from [2] is fulfilled.

$$I_{i \_{\text{max}}} = \frac{V_o}{L_r}$$

2. Non-zero-current-transition will always be occurred during main switch turn-on action. This is caused by $I_{D_c}$ (Fig. 5 waveform 5).
3. \( i_{Dc} \) also make the \( Dc \) susceptible to reverse recovery current problem during transition from state 6 to state 1 (Fig. 5 waveform 9).

Point 2 and 3 limit the converter performance in term of losses, EMI emission, and its maximal operating frequency.

IV. THE PFC CONTROL SCHEME

A. Basic Control Technique

Reference [8] pointed out that the order of small-signal control to output characteristics a ZCS-QR converter is the same to a conventional hard-switched solution. This makes the well-proven multiplier-based current-averaged PFC control scheme become preferred control candidate.

Fig. 7 shows the block diagram of the proposed PFC circuit. This control scheme is based on commercially available PFC control circuit. It consists of two control-loops; the inner current loop and the outer voltage-loop. For conventional hard-switched PFC circuit, all functions related to control circuit are normally contained inside a single chip IC. In this kind of IC, output of the average current controller is internally fetched to a PWM module.

![Control block diagram of the proposed PFC circuit](image)

However, a ZCS-QR converter is controlled by frequency modulation instead of a PWM controller. Therefore, in the proposed PFC topology, the PWM module is bypassed and an external connection to a voltage-controlled oscillator (VCO) is made.

B. Current Amplifier Gain

In order to achieve current-loop stability, the amplified inductor current down slope must not exceed the oscillator ramp slope [10]. This criterion provides a mean to determine the optimal point of the current amplifier gain \((G_{CA})\) inside the \( I_i \) Compensator on Fig. 7. \( G_{CA} \) could be solved by (2).

\[
G_{CA} = \frac{\dot{V}_{CS}}{\dot{V}_{RS}} = \frac{V_f S L_i}{V_o R_s}
\]  

\( \dot{V}_{CS} \) is the oscillator ramp slope, \( \dot{V}_{RS} \) is the current-amplifier off-time slope. In PWM controller, \( V_S \) is the peak to peak ramp voltage while in ZCS-QR controller, \( V_S \) is the input voltage range of the VCO. \( f_s \) is the switching frequency, \( L_i \) is the input inductor, \( V_o \) is the output voltage, and \( R_s \) is current sense resistance.

It is realized from (2) that due to variable frequency operation nature of the ZCS-QR control technique, the current amplifier gain should also be variable. To simplify the overall design process, in this paper, the current amplifier gain is set to be fixed on the lowest switching frequency point. It means, the circuit control performance would be slightly deteriorated while the converter operates under high switching frequency.

TABLE I

<table>
<thead>
<tr>
<th>PARAMETER LIST OF THE CONVERTERS</th>
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<tbody>
<tr>
<td>Parameter Name</td>
</tr>
<tr>
<td>( L_i )</td>
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<tr>
<td>( C_o )</td>
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<tr>
<td>( L_r )</td>
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<tr>
<td>( C_r )</td>
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<tr>
<td>( V_i )</td>
</tr>
<tr>
<td>( V_o )</td>
</tr>
<tr>
<td>( P_{in} )</td>
</tr>
<tr>
<td>Controller minimum frequency</td>
</tr>
<tr>
<td>Controller maximum frequency</td>
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</tbody>
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*) real circuit maximum input power where ZCS condition still occurs
C. Current Compensator Pole and Zero Placement

In order to determine the position of pole and zero of the \( I_i \) Compensator, the cut-off frequency \( (f_c) \) should be found first. \( f_c \) could be solved by (3) [10].

\[
f_c = \frac{f_s}{2\pi} \cdot \frac{1}{D}
\]  

\( D \) is the duty cycle. In a ZCS-QR converter, a variable called \( \mu \) is used as the equivalent value of \( D \). \( \mu \) could be found by (4) [11].

\[
\mu = f_s \cdot \left(2\pi \sqrt{L_iC_r}\right)
\]  

\( f_s \) position for the ZCS-QR topology could be determined by substituting (4) into (3). Therefore, pole and zero placements could be determined by:

\[
\text{zero} = \frac{f_s}{2} \cdot \frac{1}{f_{s_{\text{min}}}} \\
\text{pole} = f_s \cdot \frac{1}{f_{s_{\text{min}}}}
\]  

\( f_{s_{\text{min}}} \) is the minimum switching frequency of the VCO.

D. Outer-Loop Configuration

Procedure stated on [12, 13] has been followed in order to solve the outer loop parameter calculation.
VI. Conclusion

A ZCS-QR boost converter has been incorporated in a PFC circuit. With only a minor modification to the conventional PFC control circuit, compliance to the IEC61000-3-2 harmonics standard has been achieved. Reasonably high efficiency could be achieved. However, higher output voltage and faster switching frequency could suffer the converter efficiency. Potential to EMI reduction in high frequency spectrum also has been confirmed. Further investigation regarding optimization of the control technique and EMI reduction should be done.

References