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<thead>
<tr>
<th>Title</th>
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An Inverse Scattering Approach Based on the Field Equivalence Principle: Inversion without a-Priori Information on Incident Fields

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An inverse scattering approach based on the field equivalence principle is developed for reconstructing medium parameters of a scattering object. A problem equivalent to the original scattering problem internal to the measurement surface is set up. The equivalent surface currents produce a null field external to the surface, a functional of the medium parameters is introduced and a genetic algorithm is applied to the minimization of the functional. Numerical simulations for imaging defects in a known dielectric cylinder from only total field data measured on an observation surface are performed to illustrate the efficacy of the proposed inversion method. © 2010 Optical Society of America

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A variety of inverse scattering methods have been proposed for estimating the electrical parameter distributions of an unknown object from the total field measured on an observation surface last decades [1-16]. The explicit knowledge of the incident field is often assumed. Only measured total field data is, however sufficient for inversion [17].

In this paper, we propose a novel inverse scattering method for reconstructing electrical parameters of inhomogeneous objects from only measured total field data without explicitly using a-priori information regarding the incident field. The basic idea of the proposed method is based on the field equivalence principle [18]. Whatever the primary source producing fields illuminating unknown objects is, the incident field in the estimated region is calculated accurately by the equivalent surface current (related to the tangential components of the total field) on an observation surface containing the estimated region if the source is located outside the observation surface.

Let us consider a scattering problem by an inhomogeneous object embedded in a homogeneous background medium with the relative permittivity ε_0, permeability μ_0, and conductivity σ_0 as shown in Fig. 1(a). The short pulsed wave is generated by an electric current source J(r, t) where r = (x, y, z). We assume that the transmitter source is turned on at time t = 0 and there is no electromagnetic fields before time t = 0. Then, the total electromagnetic fields v(r, t) satisfy Maxwell’s equations in the following matrix form:

\[ \mathbf{L} \mathbf{v} = \mathbf{j} \]  

(1)

where

\[
\mathbf{v} = (E_x, E_y, E_z, \eta H_x, \eta H_y, \eta H_z)^t
\]

(2)

\[
\mathbf{j} = [\eta J_x, \eta J_y, \eta J_z, 0, 0, 0]^t
\]

(3)

under the initial condition of zero fields:

\[
v(r, t) = 0, \quad t < 0
\]

(4)

The superscript ‘t’ indicates ‘transposed’. \(\eta(\sqrt{\mu_0/\epsilon_0})\) is the characteristic impedance of free space. The partial differential operator \(\mathbf{L}\) is defined by

\[
\mathbf{L} = \mathbf{A} \frac{\partial}{\partial x} + \mathbf{B} \frac{\partial}{\partial y} + \mathbf{C} \frac{\partial}{\partial z} - \mathbf{F} \frac{\partial}{\partial (ct)} - \mathbf{G}
\]

(5)

where \(c(\sqrt{\epsilon_0/\mu_0})\) is the speed of light in free space, \(\mathbf{A}, \mathbf{B}, \mathbf{C}\) are 6x6 constant matrices whose components are

\[
A_{33} = -A_{33} = A_{33} = 1, \quad B_{33} = -B_{33} = B_{33} = 1, \quad C_{33} = -C_{33} = C_{33} = 1, \quad A_{44} = B_{44} = C_{44} = 0 \quad \text{otherwise, and}
\]

\[
\mathbf{F} = \begin{bmatrix} \varepsilon \mu T & 0 \\ 0 & \mu T \end{bmatrix}, \quad \mathbf{G} = \begin{bmatrix} \eta \sigma T & 0 \\ 0 & 0 \end{bmatrix}
\]

(6)

and where \(\varepsilon, \mu, \sigma\) are the relative permittivity, relative permeability, and conductivity of the medium, respectively. \(T\) denotes the 3x3 identity matrix.

Let us consider two regions, denoted by \(\Omega\) and \(\bar{\Omega}\), and separated by an observation surface \(\partial \Omega\). The impressed source \(\mathbf{J}\) is assumed to be in the region \(\bar{\Omega}\) while the scattering object in the region \(\Omega\). Let us set up a problem equivalent to the original problem internal to \(\partial \Omega\), i.e., the original field exists in \(\Omega\) and the null field in \(\bar{\Omega}\). In the equivalent problem, the original source \(\mathbf{J}\) (and obstacles if any) is removed and equivalent sources are placed on the
The homogeneous host medium \( \lambda \) is the wavelength in free space corresponding to the total fields on \( \partial \Omega \) contributes. The component \( s^{\text{inc}} \) of \( s \) corresponding to the incident field reproduces faithfully the incident field in \( \Omega \) which is scattered by the object, so that the source \( s^{\text{inc}} \) contributes to producing the scattered field over the whole region \( \Omega \cup \Omega \). In the region \( \Omega \) the negative of the scattered field produced by the source \( s^{\text{inc}} \) cancels out completely the scattered field due to the source \( s^{\text{inc}} \) and the object.

Suppose transient total field data are measured on the observation surface \( \partial \Omega \) during a time interval \([0, T]\). The time-domain inverse scattering problem under consideration here is the estimation of \( \varepsilon (r) \), \( \mu (r) \), and \( \sigma (r) \) with the knowledge of the tangential components of the original total fields \( v(r, t) \) measured on the surface \( \partial \Omega \) but without the explicit knowledge of the incident field. According to the equivalence principle, when the estimated electrical parameters are identical with the true ones, the fields produced by the equivalent surface current \( s \) cancel out the scattered fields in the region \( \Omega \) by the object so that no fields are there during the time interval \([0, T]\). Incorrectly estimated parameters, however, do not yield null fields in the region \( \Omega \). Based on this observation, we formulate the inverse problem as an optimization problem in which the following cost functional needs to be minimized:

\[
Q(p) = \sum_{n=1}^{N} \int_{0}^{T} \left| \mathbf{u}(\mathbf{p}, \mathbf{r}, t) \right|^{2} \, dt \, dr
\]

where \( p = [\varepsilon (r), \mu (r), \sigma (r)] \) is an electrical parameter vector of the object. \( N \) successive illuminations are assumed to probe the object. The vector \( \mathbf{u}(\mathbf{p}, \mathbf{r}, t) \) is the total fields for an estimated parameter \( p \) due to the \( n \)th equivalent surface current \( \mathbf{s}_{n} \), \( n = 1, \ldots, N \). Note that the surface current \( \mathbf{s}_{n} \) is given by the total fields on \( \partial \Omega \) for the object with true material parameters \( \mathbf{p}^{\text{true}} = [\varepsilon^{\text{true}}, \mu^{\text{true}}, \sigma^{\text{true}}] \) due to the \( n \)th illuminating source \( \mathbf{j}_{n} \). In practice, \( \mathbf{s}_{n} \) is determined by the total fields measured on the observation surface \( \partial \Omega \). In numerical simulations, \( \mathbf{s}_{n} \) is synthesized directly by \( \mathbf{j}_{n} \).

In order to confirm the effectiveness of the proposed method, let us examine, for simplicity's sake, a two dimensional nondestructive testing problem of retrieving the location and size of two unknown defects in a known host medium as shown in Fig. 2. The total field \( \mathbf{u}(\mathbf{r}, t) \) is calculated by the finite-difference time-domain (FDTD) method and a genetic algorithm [19] is used to minimize the cost functional \( Q(p) \). The homogeneous host medium with the relative permittivity \( \varepsilon = 4.0 \) is a square of \( 2 \lambda \times 2 \lambda \) whose center is located at the origin \((x, y) = (0, 0)\).

Here, \( \lambda \) is the wavelength in free space corresponding to: 

\[
\mathbf{u}(\mathbf{r}, t) = \begin{cases} \mathbf{v}(\mathbf{r}, t) & \mathbf{r} \in \Omega \\ 0 & \mathbf{r} \in \overline{\Omega} \end{cases}
\]

and where \( \delta_{\partial \Omega} \) is the delta function representing a source concentration on the surface \( \partial \Omega \). The source \( \mathbf{s} \) produces the same total fields as do the original source internal to \( \partial \Omega \) while the null field external to \( \partial \Omega \), i.e.,

\[
\mathbf{u}(\mathbf{r}, t) = \left\{ \begin{array}{ll} \mathbf{v}(\mathbf{r}, t) & \mathbf{r} \in \Omega \\ 0 & \mathbf{r} \in \overline{\Omega} \end{array} \right.
\]

Note that the component \( s^{\text{inc}} \) of the source \( s = s^{\text{inc}} + s^{\text{sc}} \) related to the scattered field by the object reproduces faithfully the negative of the scattered field propagating outward from \( \partial \Omega \) and does not contribute to fields in \( \Omega \). The component \( s^{\text{inc}} \) of \( s \) corresponding to the incident field reproduces faithfully the incident field in \( \Omega \) which is scattered by the object, so that the source \( s^{\text{inc}} \) contributes to producing the scattered field over the whole region \( \Omega \cup \Omega \). In the region \( \Omega \) the negative of the scattered field produced by the source \( s^{\text{inc}} \) cancels out completely the scattered field due to the source \( s^{\text{inc}} \) and the object.
the highest frequency contained in the primary source (i.e.,
the frequency at which the amplitude spectrum of the
source pulse becomes 5% of its maximum value):
\[
j_s = I(t)\delta(t - t_s)
\]
where \( r = r_s \) is the location of the \( n \)th primary source and the
time factor
\[
I(t) = \frac{d}{dt}\exp\left[-\alpha^2(t - \tau)^2\right]
\]
and where \( \tau = \beta\Delta t \), \( \alpha = 5.6/\tau \), and \( \beta = 132 \) with the
time step size \( \Delta t = 0.98(\Delta x/c\sqrt{2}) \) and the cell size
\( \Delta x = \Delta y = \lambda/10\sqrt{4} \). The defect 1 is a \( 0.3\lambda \times 0.6\lambda \) square of
\( \varepsilon_r = 1.0 \) with its centre at \((0.5\lambda, 0)\) and the defect 2 is a
\( 0.6\lambda \times 0.3\lambda \) square of \( \varepsilon_r = 1.0 \) with its centre at \((0, -0.5\lambda)\).
The measurements are performed along the periphery
\( \partial\Omega \) of the square of side \( 3\lambda \). The primary sources are
located \( \lambda \) away from the measurement line \( \partial\Omega \). The background is free space.

The parameters characterizing host medium (the
defects are assumed to
be known, while the location \((x_{1r}, y_{1r})\) of the center and the
size \( l_{1r} \times l_{1r} \) of the defect 1 and the location \((x_{2r}, y_{2r})\) of
the center and the size \( l_{2r} \times l_{2r} \) of the defect 2 are searched for.
In order to show the estimation is not affected by clutter, a
\( \lambda \times 0.3\lambda \) dielectric square obstacle with \( \varepsilon_r = 2.0 \) is placed between
the primary source and the observation surface. The
information on the blocking square as well as the
primary sources is used for calculating synthetic
measurement data, while such information is not
necessary in the inversion procedure of the proposed
method. For the use of 12 successive illuminations, the
best estimated values of the characterizing parameters in
10 runs of the GA search after 200 generations are the
same values of true ones, \((x_{1r}, y_{1r}) = (0.50\lambda, 0.00\lambda)\),
\( l_{1r} \times l_{1r} = 0.30\lambda \times 0.60\lambda \), \((x_{2r}, y_{2r}) = (0.00\lambda, -0.50\lambda)\),
and \( l_{2r} \times l_{2r} = 0.60\lambda \times 0.30\lambda \). The successful estimation
demonstrates the effectiveness of the present approach.
Interestingly, for a single illumination by any of the 12
sources, satisfactory results were also obtained.

In conclusion, we have presented an inverse scattering
approach for reconstructing material parameters of an
object of interest which does not require explicitly \textit{a priori}
knowledge of incident fields. This indicates that even in
the presence of any obstacle (know or unknown) near the
primary source we do not need to calculate the scattered
field by the obstacle if it locates outside the region
enclosed by the observation surface. The sum of the field
generated by the primary source and the scattered field
by the obstacle is regarded as the incident field. The
measured total fields consist of the incident field and the
scattered field by the object of interest. The material
parameters of the object are estimated from the measured
total field data only. We close with three remarks. The
proposed approach can be applied to whatever temporal
regime and the time-dependence used in the numerical
examples is just for this presentation. In order to avoid
computational complexity growing rapidly with the
number of unknowns when using GAs, gradient-based
optimization procedures are preferable. In practice a finite
number of measurement points are used. We must
examine how sparsely the measurement points can be
located to get satisfactory reconstruction results. These
issues will be considered in future studies.

References

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